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Cooperative Robots and Sensor Networks 2014

Cooperative Robots And Sensor Networks 2014 Studies In Computational Intelligence

**Anis Koubâa, J. Ramiro Martínez-de
Dios**



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Cooperative Robots and Sensor Networks 2014 Anis Koubaa, Abdelmajid Khelil, 2014-05-21 This book is the second volume on Cooperative Robots and Sensor Networks The primary objective of this book is to provide an up to date reference for cutting edge studies and research trends related to mobile robots and wireless sensor networks and in particular for the coupling between them Indeed mobile robots and wireless sensor networks have enabled great potentials and a large space for ubiquitous and pervasive applications Robotics and wireless sensor networks have mostly been considered as separate research fields and little work has investigated the marriage between these two technologies However these two technologies share several features enable common cyber physical applications and provide complementary support to each other The book consists of ten chapters organized into four parts The first part of the book presents three chapters related to localization of mobile robots using wireless sensor networks Two chapters presented new solutions based Extended Kalman Filter and Particle Filter for localizing the robots using range measurements with the sensor network The third chapter presents a survey on mobility assisted localization techniques in wireless sensor networks The second part of the book deals with cooperative robots and sensor networks applications One chapter presents a comprehensive overview of major applications coupling between robots and sensor networks and provides real world examples of their cooperation Two other chapters present applications for underwater robots and sensor networks

Cooperative Robots and Sensor Networks 2015 Anis Koubaa, J. Ramiro Martínez-de Dios, 2015-05-18 This book compiles some of the latest research in cooperation between robots and sensor networks Structured in twelve chapters this book addresses fundamental theoretical implementation and experimentation issues The chapters are organized into four parts namely multi robots systems data fusion and localization security and dependability and mobility

Robot 2015: Second Iberian Robotics Conference Luís Paulo Reis, António Paulo Moreira, Pedro U. Lima, Luis Montano, Victor Muñoz-Martinez, 2015-12-01 This book contains a selection of papers accepted for presentation and discussion at ROBOT 2015 Second Iberian Robotics Conference held in Lisbon Portugal November 19th 21th 2015 ROBOT 2015 is part of a series of conferences that are a joint organization of SPR Sociedade Portuguesa de Rob tica Portuguese Society for Robotics SEIDROB Sociedad Espa ola para la Investigaci n y Desarrollo de la Rob tica Spanish Society for Research and Development in Robotics and CEA GTRob Grupo Tem tico de Rob tica Robotics Thematic Group The conference organization had also the collaboration of several universities and research institutes including University of Minho University of Porto University of Lisbon Polytechnic Institute of Porto University of Aveiro University of Zaragoza University of Malaga LIACC INESC TEC and LARSyS Robot 2015 was focussed on the Robotics scientific and technological activities in the Iberian Peninsula although open to research and delegates from other countries The conference featured 19 special sessions plus a main general robotics track The special sessions were about Agricultural Robotics and Field Automation Autonomous Driving and Driver Assistance Systems Communication Aware Robotics

Environmental Robotics Social Robotics Intelligent and Adaptable AAL Systems Future Industrial Robotics Systems Legged Locomotion Robots Rehabilitation and Assistive Robotics Robotic Applications in Art and Architecture Surgical Robotics Urban Robotics Visual Perception for Autonomous Robots Machine Learning in Robotics Simulation and Competitions in Robotics Educational Robotics Visual Maps in Robotics Control and Planning in Aerial Robotics the XVI edition of the Workshop on Physical Agents and a Special Session on Technological Transfer and Innovation

Deep Learning Model Optimization, Deployment and Improvement Techniques for Edge-native Applications Pethuru Raj, Gayathri Nagasubramanian, 2024-08-22 The edge AI implementation technologies are fast maturing and stabilizing Edge AI digitally transforms retail manufacturing healthcare financial services transportation telecommunication and energy The transformative potential of Edge AI a pivotal force in driving the evolution from Industry 4.0's smart manufacturing and automation to Industry 5.0's human centric sustainable innovation The exploration of the cutting edge technologies tools and applications that enable real time data processing and intelligent decision making at the network's edge addressing the increasing demand for efficiency resilience and personalization in industrial systems Our book aims to provide readers with a comprehensive understanding of how Edge AI integrates with existing infrastructures enhances operational capabilities and fosters a symbiotic relationship between human expertise and machine intelligence Through detailed case studies technical insights and practical guidelines this book serves as an essential resource for professionals researchers and enthusiasts poised to harness the full potential of Edge AI in the rapidly advancing industrial landscape

Communicating Process Architectures 2015 & 2016 K. Chalmers, J. Bækgaard Pedersen, F.R.M. Barnes, 2018-10-04 This book presents the proceedings of two conferences the 37th and 38th in the WoTUG series Communicating Process Architectures CPA 2015 held in Canterbury England in August 2015 and CPA 2016 held in Copenhagen Denmark in August 2016 Fifteen papers were accepted for presentation at the 2015 conference They cover a spectrum of concurrency concerns mathematical theory programming languages design and support tools verification multicore infrastructure and applications ranging from supercomputing to embedded Three workshops and two evening fringe sessions also formed part of the conference and the workshop position papers and fringe abstracts are included in this book Fourteen papers covering the same broad spectrum of topics were presented at the 2016 conference one of them in the form of a workshop They are all included here together with abstracts of the five fringe sessions from the conference

Approximation and Online Algorithms Evripidis Bampis, Ola Svensson, 2015-04-22 This book constitutes the thoroughly refereed post workshop proceedings of the 12th International Workshop on Approximation and Online Algorithms WAOA 2014 held in Wrocław Poland in September 2014 as part of ALGO 2014 The 22 revised full papers presented were carefully reviewed and selected from 49 submissions They cover a wide range of topics such as coloring and partitioning competitive analysis network design packing and covering paradigms for design and analysis of approximation and online algorithms randomization techniques real world applications and scheduling

problems Conservation Technology Serge A. Wich,Alex K. Piel,2021-08-31 The global loss of biodiversity is occurring at an unprecedented pace Despite the considerable effort devoted to conservation science and management we still lack even the most basic data on the distribution and density of the majority of plant and animal species which in turn hampers our efforts to study changes over time In addition we often lack behavioural data from the very animals most influenced by environmental changes this is largely due to the financial and logistical limitations associated with gathering scientific data on species that are cryptic widely distributed range over large areas or negatively influenced by human presence To overcome these limitations conservationists are increasingly employing technology to facilitate such data collection Innovative solutions have been driven by dramatic advances in the conservation technology interface The use of camera traps acoustic sensors satellite data drones and computer algorithms to analyse the large datasets collected are all becoming increasingly widespread Although specialist books are available on some of these individual technologies this is the first comprehensive text to describe the breadth of available technology for conservation and to evaluate its varied applications bringing together a team of international experts using a diverse range of approaches Conservation Technology is suitable for graduate level students professional researchers practitioners and field managers in the fields of ecology and conservation biology Human Interaction and Emerging Technologies Tareq Ahram,Redha Taiar,Serge Colson,Arnaud Choplin,2019-07-24 This book reports on research and developments in human technology interaction A special emphasis is given to human computer interaction and its implementation for a wide range of purposes such as healthcare aerospace telecommunication and education among others The human aspects are analyzed in detail Timely studies on human centered design wearable technologies social and affective computing augmented virtual and mixed reality simulation human rehabilitation and biomechanics represent the core of the book Emerging technology applications in business security and infrastructure are also critically examined thus offering a timely scientifically grounded but also professionally oriented snapshot of the current state of the field The book is based on contributions presented at the 1st International Conference on Human Interaction and Emerging Technologies IHiet 2019 held on August 22 24 in Nice France It offers a timely survey and a practice oriented reference guide to systems engineers psychologists sport scientists physical therapists as well as decision makers designing or dealing with the new generation of service systems User Experience of a Social Media Based Knowledge Sharing System in Industry Work Chapter of this book is available open access under a CC BY 4 0 license at link springer com **Connectivity Prediction in Mobile Ad Hoc Networks for Real-Time Control** Sebastian Thelen,2015-09-21 Cyber physical systems are the next step in realizing the centuries old ubiquitous computing idea by focusing on open real time systems design and device connectivity Mobile ad hoc networks offer the flexible local connectivity that cyber physical systems require if the connectivity can be realized dependably One aspect of the dependability is the prediction of connectivity in the mobile ad hoc network The presented research contributes to the connectivity prediction in mobile ad hoc

networks with moving network participants in two ways It systematically analyses the influence of scenario parameters on a set of connectivity metrics and it proposes and evaluates three classes of prediction models for these metrics

Computational Intelligence, Networked Systems and Their Applications Minrui Fei,Chen Peng,Zhou Su,Yang Song,Qinglong Han,2014-10-01 This book constitutes the second part of the refereed proceedings of the International Conference on Life System Modeling and Simulation LSMS 2014 and of the International Conference on Intelligent Computing for Sustainable Energy and Environment ICSEE 2014 held in Shanghai China in September 2014 The 159 revised full papers presented in the three volumes of CCIS 461 463 were carefully reviewed and selected from 572 submissions The papers of this volume are organized in topical sections on advanced neural network theory and algorithms advanced evolutionary computing theory and algorithms such as particle swarm optimization differential evolution ant colonies artificial life artificial immune systems and genetic algorithm fuzzy neural and fuzzy neuro hybrids intelligent modeling monitoring and control of complex nonlinear systems intelligent modeling and simulation of climate change communication and control for distributed networked systems

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