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into the world of UAVs The materials are intended to provide enough information in each area and illustrate how they all play together to support the design of a complete UAV Therefore this book can be used both as a reference for engineers entering the field or as a supplementary text for a UAV design course to provide system level context for each specialized topic

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closed form optimal controllers for the powerful class of fast sampled constrained piecewise affine systems These systems may exhibit rather complex behavior and are equivalent to many other hybrid system formalisms combining continuous valued dynamics with logic rules reported in the literature Furthermore piecewise affine systems are a useful modeling tool that can capture general nonlinearities e g by local approximation constraints saturations switches and other hybrid modeling phenomena The first part of the book presents an introduction to the mathematical and control theoretical background material needed for the full understanding of the book The second part provides an in depth look at the computational and control theoretic properties of the controllers and part three presents different analysis and post processing techniques

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